KFT SOLUTIONS 03

1. INHOMOGENEOUS MAXWELL-EQUATIONS AND POTENTIALS

(a) Under the gauge transformation $A_{\beta} \rightarrow A_{\beta} + \partial_{\beta} \Psi$, $F_{\alpha\beta}$ transforms as

$$\partial_{\alpha}A_{\beta} - \partial_{\beta}A_{\alpha} \to \partial_{\alpha}A_{\beta} + \partial_{\alpha}\partial_{\beta}\Psi - \partial_{\beta}A_{\alpha} - \partial_{\beta}\partial_{\alpha}\Psi = \partial_{\alpha}A_{\beta} - \partial_{\beta}A_{\alpha}$$
(1)

and therefore $F_{\alpha\beta}$ is gauge-invariant.

(b) With $A_{\alpha} = (-\phi/c, \vec{A})$ one has

$$F_{0k} = -F_{k0} = \partial_0 A_k - \partial_k A_0 = c^{-1} (\partial_t A_k + \partial_k \phi) = -E_k/c$$

$$F_{ik} = \partial_i A_k - \partial_k A_i = \epsilon_{ik\ell} B_\ell \quad (F_{12} = B_3 \quad \text{etc.})$$
(2)

and therefore, with $F^{\alpha\beta} = \eta^{\alpha\gamma}\eta^{\beta\delta}F_{\gamma\delta}$,

$$F^{0k} = -F^{k0} = -F_{0k} = E_k/c$$
 , $F^{ik} = F_{ik} = \epsilon_{ik\ell}B_\ell$. (3)

(c) Thus, with $J^{\alpha} = (\rho c, \vec{J})$ one has

$$\partial_{\alpha}F^{\alpha 0} = \partial_{k}F^{k0} = -c^{-1}\vec{\nabla}.\vec{E} = -\rho/(\epsilon_{0}c) = -\mu_{0}c\rho = -\mu_{0}J^{0}$$
(4)

and

$$\partial_{\alpha}F^{\alpha 1} = \partial_{0}F^{01} + \partial_{2}F^{21} + \partial_{3}F^{31} = c^{-2}\partial_{t}E_{1} - \partial_{2}B_{3} + \partial_{3}B_{2}$$

= $-(\vec{\nabla} \times \vec{B} - \frac{1}{c^{2}}\partial_{t}\vec{E})_{1} = -\mu_{0}J_{1} = -\mu_{0}J^{1}$ (5)

(and likewise for the 2- and 3-components).

(d) One has

$$\partial_{\alpha}F^{\alpha\beta} = \partial_{\alpha}\partial^{\alpha}A^{\beta} - \partial_{\alpha}\partial^{\beta}A^{\alpha} = \Box A^{\beta} - \partial^{\beta}\partial_{\alpha}A^{\alpha} = -\mu_0 J^{\beta}$$
(6)

and therefore $\Box A_{\beta} - \partial_{\beta}\partial_{\alpha}A^{\alpha} = -\mu_0 J_{\beta}$.

(e) One has

$$\Box (A_{\beta} + \partial_{\beta} \Psi) - \partial_{\beta} \partial_{\alpha} (A^{\alpha} + \partial^{\alpha} \Psi) = \Box A_{\beta} + \partial_{\beta} \Box \Psi - \partial_{\beta} \partial_{\alpha} A^{\alpha} - \partial_{\beta} \Box \Psi$$
(7)

Since the $\Box \Psi$ -term cancels, the expression is gauge invariant.

(f) From $\partial_{\alpha}F^{\alpha\beta} = -\mu_0 J^{\beta}$ one deduces $-\mu_0 \partial_{\beta}J^{\beta} = \partial_{\beta}\partial_{\alpha}F^{\alpha\beta} = 0$ because $F^{\alpha\beta} = -F^{\beta\alpha}$ is anti-symmetric while $\partial_{\alpha}\partial_{\beta} = \partial_{\beta}\partial_{\alpha}$ is symmetric.

2. The Homogeneneous Maxwell-Equations

(a) One has $\partial_{\alpha}F_{\beta\gamma} = \partial_{\alpha}\partial_{\beta}A_{\gamma} - \partial_{\alpha}\partial_{\gamma}A_{\beta}$ etc. Using the fact that 2nd partial derivatives commute one deduces

$$\partial_{\alpha}F_{\beta\gamma} + \partial_{\gamma}F_{\alpha\beta} + \partial_{\beta}F_{\gamma\alpha} = \partial_{\alpha}\partial_{\beta}A_{\gamma} - \partial_{\gamma}\partial_{\alpha}A_{\beta} + \partial_{\gamma}\partial_{\alpha}A_{\beta} - \partial_{\beta}\partial_{\gamma}A_{\alpha} + \partial_{\beta}\partial_{\gamma}A_{\alpha} - \partial_{\alpha}\partial_{\beta}A_{\gamma} = 0$$
(8)

(b) $\partial_{\alpha}F_{\beta\gamma} + \partial_{\beta}F_{\gamma\alpha} + \partial_{\gamma}F_{\alpha\beta} = 0$

- i. Two indices equal $(\alpha = \beta, \text{say})$: $\partial_{\alpha}F_{\alpha\gamma} + \partial_{\alpha}F_{\gamma\alpha} + \partial_{\gamma}F_{\alpha\alpha} = 0$ is identically satisfied because $F_{\alpha\alpha} = 0$, $F_{\alpha\gamma} + F_{\gamma\alpha} = 0$.
- ii. All 3 indices spatial, $(\alpha, \beta, \gamma) = (1, 2, 3)$:

$$\partial_1 F_{23} + \partial_2 F_{31} + \partial_3 F_{21} = \partial_1 B_1 + \partial_2 B_2 + \partial_3 B_3 = \vec{\nabla} \cdot \vec{B} = 0 \qquad (9)$$

iii. One index time, the others spatial, e.g. $(\alpha, \beta, \gamma) = (0, 1, 2)$:

$$\partial_0 F_{12} + \partial_1 F_{20} + \partial_2 F_{01} = c^{-1} (\partial_t B_3 + \partial_1 E_2 - \partial_2 E_1) = c^{-1} (\vec{\nabla} \times \vec{E} + \partial_t \vec{B})_3 = 0$$
(10)

(and likewise for the other components).

3. The dual field strength tensor

The dual field strength tensor is defined by

$$\tilde{F}^{\alpha\beta} = \frac{1}{2} \epsilon^{\alpha\beta\gamma\delta} F_{\gamma\delta} \quad . \tag{11}$$

With $F_{0i} = -c^{-1}E_i$, $F_{ij} = \epsilon_{ijk}B_k$ and $\tilde{F}^{\alpha\beta} = \frac{1}{2}\epsilon^{\alpha\beta\gamma\delta}F_{\gamma\delta}$ one gets for the non-zero components of $\tilde{F}^{\alpha\beta}$:

$$\tilde{F}^{0i} = \frac{1}{2} \epsilon^{0i\gamma\delta} F_{\gamma\delta} = \frac{1}{2} \epsilon^{0ijk} F_{jk} = \frac{1}{2} \epsilon^{0ijk} \epsilon_{jkl} B_l = -B_i$$
(12)

$$\tilde{F}^{ij} = \frac{1}{2} \epsilon^{ij\gamma\delta} F_{\gamma\delta} = \epsilon^{ij0k} F_{0k} = -c^{-1} \epsilon^{ij0k} E_k = c^{-1} \epsilon^{ijk} E_k .$$
(13)

The equation $\partial_{\lambda} \tilde{F}^{\lambda\delta} = 0$ can then be written as

$$\partial_{\lambda} \tilde{F}^{\lambda 0} = -\partial_{i} \tilde{F}^{0i} = \vec{\nabla} \cdot \vec{B}$$
(14)

$$\tilde{F}^{\lambda j} = \partial_0 \tilde{F}^{0j} + \partial_i \tilde{F}^{ij} = -c^{-1} \partial_t B_j - c^{-1} \epsilon_{jik} \partial_i E_k
= -\frac{1}{c} \left(\partial_t \vec{B} + \vec{\nabla} \times \vec{E} \right)_j,$$
(15)

which proves the assertion.

 ∂_{λ}

4. LORENTZ INVARIANTS

(a)

$$I_{1} = \frac{1}{4}F_{\alpha\beta}F^{\alpha\beta} = \frac{1}{4}\left(F_{0i}F^{0i} + F_{i0}F^{i0} + F_{ij}F^{ij}\right)$$

$$= \frac{1}{2}\left(-(F_{0i})^{2} + (F_{ij})^{2}\right) = \frac{1}{2}\left(\vec{B}^{2} - c^{-2}\vec{E}^{2}\right)$$

$$I_{2} = \frac{1}{4}F_{\alpha\beta}\tilde{F}^{\alpha\beta} = \frac{1}{4}\left(F_{0i}\tilde{F}^{0i} + F_{i0}\tilde{F}^{i0} + F_{ij}\tilde{F}^{ij}\right)$$

(16)

$$= \frac{1}{4} \left(2c^{-1}E_i B_i + \epsilon_{ijk} B_k c^{-1} \epsilon^{ijl} E_l \right) = c^{-1} \vec{E} \cdot \vec{B}$$
(17)

where one has used $\epsilon^{ijl}\epsilon_{ijk} = 2\delta_k^l$. If $\vec{E} = 0$ in one inertial system, then $I_1 > 0$ and $I_2 = 0$ in all inertial systems, and thus $\vec{E}.\vec{B} = 0$ and $|\vec{E}| < |\vec{B}|$ in all inertial systems.

(b)

$$8I_2 = \epsilon^{\alpha\beta\gamma\delta}F_{\alpha\beta}F_{\gamma\delta} = 2\epsilon^{\alpha\beta\gamma\delta}(\partial_{\alpha}A_{\beta})F_{\gamma\delta} = 2\partial_{\alpha}\left(\epsilon^{\alpha\beta\gamma\delta}A_{\beta}F_{\gamma\delta}\right)$$
(18)

because $\epsilon^{\alpha\beta\gamma\delta}\partial_{\alpha}F_{\gamma\delta} = 0$ (Bianchi identity). Thus I_2 is a total derivative, $I_2 = \partial_{\alpha}C^{\alpha}$. C^{α} is not gauge invariant but changes by a total derivative under a gauge transformation,

$$\epsilon^{\alpha\beta\gamma\delta}A_{\beta}F_{\gamma\delta} \to \epsilon^{\alpha\beta\gamma\delta}\partial_{\beta}\psi F_{\gamma\delta} = \partial_{\beta}(\epsilon^{\alpha\beta\gamma\delta}\psi F_{\gamma\delta}) \tag{19}$$

5. Lorentz transformation of \vec{B} :

Using $\bar{F}_{\alpha\beta} = \Lambda_{\alpha}^{\gamma} \Lambda_{\beta}^{\delta} F_{\gamma\delta}$ one wants to compute the transformation of \bar{F}_{ij} which contains the magnetic field components. To do this we need Λ_{α}^{β} which is obtained from L_{β}^{α} by inverse transposition, which gives

$$\left(\Lambda_{\alpha}^{\ \beta}\right) = \begin{pmatrix} \cosh \alpha & \sinh \alpha & 0 & 0\\ \sinh \alpha & \cosh \alpha & 0 & 0\\ 0 & 0 & 1 & 0\\ 0 & 0 & 0 & 1 \end{pmatrix} .$$
(20)

With it one computes :

$$\bar{F}_{ij} = \Lambda_i^{\gamma} \Lambda_j^{\delta} F_{\gamma\delta} = \Lambda_i^0 \Lambda_j^l F_{0l} + \Lambda_i^k \Lambda_j^0 F_{k0} + \Lambda_i^k \Lambda_j^l F_{kl}$$
$$= \left(\Lambda_i^0 \Lambda_j^l - \Lambda_i^l \Lambda_j^0\right) F_{0l} + \Lambda_i^k \Lambda_j^l F_{kl}$$
(21)

such that

$$\bar{F}_{12} = \sinh \alpha F_{02} + \cosh \alpha F_{12} = -c^{-1}\gamma \beta E_2 + \gamma B_3$$
 (22)

$$\bar{F}_{23} = F_{23}$$
 (23)

$$\bar{F}_{31} = -\sinh \alpha F_{03} + \cosh \alpha F_{31} = c^{-1} \gamma \beta E_3 + \gamma B_2$$
(24)

from which one can read off the transformation of the magnetic field :

$$\bar{B}_1 = B_1$$

$$\bar{B}_2 = \gamma B_2 + c^{-1} \beta \gamma E_3$$

$$\bar{B}_3 = \gamma B_3 - c^{-1} \beta \gamma E_2$$
(25)