1. Die Lorentz-Gruppe

(a) The first claim follows from multiplicativity of the determinant (and invariance under transposition):

$$L^T \eta L = \eta \quad \Rightarrow \quad \det(L^T \eta L) = \det(\eta) \quad \Rightarrow \quad \det(L)^2 = +1 \quad .$$
 (1)

The second claim follows for writing $(L^T \eta L)_{00} = \eta_{00}$ explicitly,

$$\eta_{\alpha\beta}L_0^{\alpha}L_0^{\beta} \stackrel{!}{=} \eta_{00} = -1$$

$$\Rightarrow \quad \eta_{00}L_0^0L_0^0 + \eta_{ik}L_0^iL_0^k = -(L_0^0)^2 + \delta_{ik}L_0^iL_0^k = -1 \quad (2)$$

$$\Rightarrow \quad (L_0^0)^2 = 1 + \delta_{ik}L_0^iL_0^k \ge 1 \quad .$$

(b) It is trivial to verify that

$$L_1^T \eta L_1 = \eta, L_2^T \eta L_2 = \eta \quad \Rightarrow \quad (L_1 L_2)^T \eta (L_1 L_2) = \eta \quad .$$
 (3)

Existence of an inverse L^{-1} follows from det $L \neq 0$ (shown above). That $L \in \mathcal{L} \Rightarrow L^{-1} \in \mathcal{L}$ follows from

$$L^T \eta L = \eta \quad \Leftrightarrow \quad \eta = (L^{-1})^T \eta L^{-1} \quad . \tag{4}$$

2. Geometrie : Analytische Minkowski-Geometrie

(a) Because of Lorentz invariance one can choose to work in the rest frame in which v = (a, 0, 0, 0). A general null vector $w = (w^0, w^1, w^2, w^3)$ is such that $(w^0)^2 = (w^1)^2 + (w^2)^2 + (w^3)^2$ and we want $v = w_1 + w_2$. With the choice $w_1^0 = w_2^0 = \frac{a}{2}$ one possibility is

$$w_1 = (\frac{a}{2}, \frac{a}{2}, 0, 0) \quad w_2 = (\frac{a}{2}, -\frac{a}{2}, 0, 0) \quad .$$
 (5)

(b) Assuming v = (a, a, 0, 0) a general null vector in a preferred frame (with $a \neq 0$), then the orthogonality condition with w gives

$$v.w = a(w^1 - w^0) = 0 \quad \Rightarrow \quad w^0 = w^1 ,$$
 (6)

with w^2 and w^3 unconstrained. Therefore the square of w gives :

$$w.w = -(w^{0})^{2} + (w^{1})^{2} + (w^{2})^{2} + (w^{3})^{2}$$

= $(w^{2})^{2} + (w^{3})^{2} \ge 0 \iff \text{Not timelike}$ (7)

and is equal to zero if and only if $w^2 = w^3 = 0$ which implies $v = \lambda w$ for some constant λ .

(c) The sum of two timelike vectors is *not* necessarily timelike. As a counterexample, consider the vectors u = (a, b, 0, 0) and v = (-a, b, 0, 0); these are timelike for |b| < |a| but their sum u + v = (0, 2b, 0, 0) is clearly spacelike. What *is* true is that the sum of two future-pointing $(u^0 > 0, v^0 > 0)$ timelike vectors is future-pointing and timelike.

Likewise, the sum of two spacelike vectors is *not* necessarily spacelike. As a counterexample, consider the vectors u = (a, b, 0, 0) and v = (a, -b, 0, 0); these are spacelike for |b| > |a| but their sum u + v = (2a, 0, 0, 0) is clearly timelike. This shows that one should not think that for spacelike vectors Minkowski geometry reduces to Euclidean geometry.

3. TENSOR-ALGEBRA: LORENTZ-TENSOREN

By definition a Lorentz vector transforms as

$$\bar{v}^{\alpha} = L^{\alpha}_{\ \beta} v^{\beta} \quad , \tag{8}$$

and a Lorentz covector as

$$\bar{u}_{\alpha} = \Lambda_{\alpha}^{\ \beta} u_{\beta} \quad , \tag{9}$$

with

$$\Lambda = (L^T)^{-1} \quad \Leftrightarrow \quad \Lambda^{\ \beta}_{\alpha} L^{\alpha}_{\ \gamma} = \delta^{\beta}_{\ \gamma} \ . \tag{10}$$

This definition is such that the *contraction* between a vector and a covector is a *scalar* (invariant under Lorentz transformations),

$$\bar{u}_{\alpha}\bar{v}^{\alpha} = \Lambda^{\ \beta}_{\alpha}L^{\alpha}_{\ \gamma}u_{\beta}v^{\gamma} = \delta^{\beta}_{\ \gamma}u_{\beta}v^{\gamma} = u_{\beta}v^{\beta} = u_{\alpha}v^{\alpha} \quad . \tag{11}$$

Higher rank tensors transform like products of vectors and covectors, i.e. a (p,q) tensor transforms with p factors of L and q factors of Λ and is written as an object with p upper indices and q lower indices.

By the same calculation as above one then finds that any contracted pair of indices on a tensor is invariant (and therefore the tensor type of the resulting object can be read off just by looking at the number of uncontracted upper and lower indices). For example:

(a) for the contraction of a (2,0)-tensor and a (0,1)-tensor (covector) one has

$$\bar{T}^{\alpha\beta}\bar{u}_{\beta} = L^{\alpha}_{\ \gamma}L^{\beta}_{\ \delta}\ T^{\gamma\delta}\ \Lambda^{\ \rho}_{\beta}u_{\rho} = L^{\alpha}_{\ \gamma}\ \delta^{\rho}_{\ \delta}\ T^{\gamma\delta}u_{\rho} = L^{\alpha}_{\ \gamma}\left(T^{\gamma\delta}u_{\delta}\right) \tag{12}$$

so that $T^{\alpha\beta}u_{\beta}$ transforms like (and therefore is) a (1,0)-tensor (vector).

(b) likewise the trace of a (1, 1)-tensor is a scalar,

$$\bar{T}^{\alpha}_{\ \alpha} = L^{\alpha}_{\ \beta}\Lambda^{\gamma}_{\ \alpha}T^{\beta}_{\ \gamma} = \delta^{\gamma}_{\ \beta}T^{\beta}_{\ \gamma} = T^{\beta}_{\ \beta} \tag{13}$$

Note that the trace of a (0,2)-tensor $T_{\alpha\beta}$ is not well-defined without using the Minkowski metric, i.e. something like

$$\operatorname{trace}(T_{\alpha\beta}) \stackrel{?}{=} \sum_{\alpha} T_{\alpha\alpha} \qquad (???) \tag{14}$$

is not Lorentz-invariant and therefore depends on the inertial system in which it is evaluated. However, with the help of the Minkowski metric one can define a Lorentz-invariant trace (i.e. a scalar) via

$$T_{\alpha\beta} \to T^{\alpha}_{\ \beta} = \eta^{\alpha\gamma}T_{\gamma\beta} \to T^{\alpha}_{\ \alpha} = \eta^{\alpha\gamma}T_{\gamma\alpha} \qquad \checkmark \tag{15}$$

("taking the trace with respect to η "). This is now manifestly a scalar.

4. TENSOR-ANALYSIS: LORENTZ-TENSOREN UND IHRE ABLEITUNGEN

The formalism is designed in such a way that the transformation behaviour (tensorial nature) can just be read off from the free indices. In particular, the partial derivative $(\partial/\partial x^{\alpha}) = \partial_{\alpha}$ transforms as a covector,

$$\bar{\partial}_{\alpha} \equiv \frac{\partial}{\partial \bar{x}^{\alpha}} = \Lambda_{\alpha}^{\ \beta} \partial_{\beta} \quad . \tag{16}$$

Thus ∂_{α} acting on a (p,q)-tensor gives a (p,q+1)-tensor.

Then the answers are trivially (a) $\partial_{\alpha} f$ covector (b) $V^{\alpha} \partial_{\alpha} f$ scalar (c) $V^{\alpha} \partial_{\beta} f$ (1,1)tensor (d) $\partial_{\alpha} V^{\alpha}$ scalar (e) $f \partial_{\alpha} V^{\alpha}$ scalar (f) $\partial_{\alpha} V_{\beta}$ (0,2)-tensor (g) $\partial_{\alpha} \partial_{\beta} f$ (0,2)tensor (h) $V^{\alpha} \partial_{\beta} V_{\alpha}$ covector.