

## 1. GEODESICS

(a) Take the Lagrangian to be :

$$\mathcal{L}(x^\mu, \dot{x}^\mu) = \frac{1}{2} g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} = \frac{1}{2} g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu \quad (1)$$

where  $g_{\mu\nu} = g_{\mu\nu}(x^\rho)$  and then compute :

$$\frac{\partial \mathcal{L}}{\partial x^\mu} = \frac{1}{2} \dot{x}^\rho \dot{x}^\nu \partial_\mu g_{\rho\nu} \quad (2)$$

$$\frac{\partial \mathcal{L}}{\partial \dot{x}^\mu} = g_{\rho\nu} \dot{x}^\rho \frac{\partial}{\partial \dot{x}^\mu} \dot{x}^\nu = g_{\rho\nu} \dot{x}^\rho \delta_\mu^\nu = g_{\rho\mu} \dot{x}^\rho \quad (3)$$

$$\frac{d}{d\tau} \left( \frac{\partial \mathcal{L}}{\partial \dot{x}^\mu} \right) = g_{\rho\mu} \ddot{x}^\rho + \dot{x}^\rho \dot{x}^\nu \partial_\nu g_{\rho\mu} = g_{\rho\mu} \ddot{x}^\rho + \frac{1}{2} (\dot{x}^\rho \dot{x}^\nu \partial_\nu g_{\rho\mu} + \dot{x}^\nu \dot{x}^\rho \partial_\rho g_{\nu\mu}) \quad (4)$$

The Euler-Lagrange equations becomes :

$$\left[ \text{E.-L.} \right] = g_{\mu\rho} \ddot{x}^\rho + \frac{1}{2} (\partial_\nu g_{\rho\mu} + \partial_\rho g_{\nu\mu} - \partial_\mu g_{\rho\nu}) \dot{x}^\nu \dot{x}^\rho \quad (5)$$

$$= g_{\mu\rho} \ddot{x}^\rho + \Gamma_{\mu\nu\rho} \dot{x}^\rho \dot{x}^\nu = 0 \quad (6)$$

and they can be written in the usual (geodesic equations) form by multiplying by  $g^{\lambda\mu}$  to move the index  $\mu$  up :

$$g^{\lambda\mu} (g_{\mu\rho} \ddot{x}^\rho + \Gamma_{\mu\nu\rho} \dot{x}^\rho \dot{x}^\nu) = \ddot{x}^\lambda + \Gamma_{\nu\rho}^\lambda \dot{x}^\rho \dot{x}^\nu = 0 \quad (7)$$

(b) First we compute :

$$\frac{d}{d\tau} \mathcal{L} = \frac{1}{2} \frac{d}{d\tau} g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu = \frac{1}{2} \left( 2g_{\mu\nu} \ddot{x}^\mu \dot{x}^\nu + (\dot{x}^\rho \partial_\rho g_{\mu\nu}) \dot{x}^\mu \dot{x}^\nu \right) \quad (8)$$

Now using the identity :

$$\partial_\rho g_{\mu\nu} = \Gamma_{\mu\nu\rho} + \Gamma_{\nu\mu\rho} \quad (9)$$

together with the fact that  $x^\mu(\tau)$  is a solution to the geodesic equation, which means that we also have :

$$\ddot{x}^\mu = -\Gamma_{\nu\rho}^\mu \dot{x}^\nu \dot{x}^\rho \quad (10)$$

leaves us with :

$$\frac{d}{d\tau} \mathcal{L} = \frac{1}{2} \left( -2g_{\mu\nu} \Gamma_{\lambda\rho}^\mu \dot{x}^\lambda \dot{x}^\rho \dot{x}^\nu + \dot{x}^\rho (\Gamma_{\mu\nu\rho} + \Gamma_{\nu\mu\rho}) \dot{x}^\mu \dot{x}^\nu \right) \quad (11)$$

$$= \frac{1}{2} \left( -2\Gamma_{\nu\lambda\rho} \dot{x}^\lambda \dot{x}^\rho \dot{x}^\nu + (\Gamma_{\mu\nu\rho} + \Gamma_{\nu\mu\rho}) \dot{x}^\mu \dot{x}^\nu \dot{x}^\rho \right) = 0 \quad (12)$$

which is obviously zero if we relabel the indices.

(c) The metric on the 2-sphere is :

$$ds^2 = R^2 \left( d\theta^2 + \sin^2(\theta)d\phi^2 \right) \quad (13)$$

so that in the  $(\theta, \phi)$  coordinates we have :

$$g_{\mu\nu} = R^2 \begin{pmatrix} 1 & 0 \\ 0 & \sin(\theta)^2 \end{pmatrix} \quad g^{\mu\nu} = R^{-2} \begin{pmatrix} 1 & 0 \\ 0 & \sin(\theta)^{-2} \end{pmatrix} \quad (14)$$

Because  $g_{\mu\nu}$  is diagonal and  $g_{\mu\nu} = g_{\mu\nu}(\theta)$ , the only non-vanishing contribution to the Christoffel's will come from  $\partial_\theta g_{\phi\phi}$ . Keeping this in mind, we can find out all the Christoffel symbols that have this term. We first compute terms with  $\theta$  on the top :

$$\Gamma_{\nu\lambda}^\theta = \frac{1}{2} g^{\theta\theta} (\partial_\lambda g_{\theta\nu} + \partial_\nu g_{\theta\lambda} - \partial_\theta g_{\nu\lambda}) = -\frac{1}{2} g^{\theta\theta} \partial_\theta g_{\nu\lambda} \quad (15)$$

and we see that the only non-vanishing term with  $\theta$  on the top is  $\Gamma_{\phi\phi}^\theta$  :

$$\Gamma_{\phi\phi}^\theta = -\frac{1}{2} g^{\theta\theta} \partial_\theta g_{\phi\phi} = -\sin(\theta) \cos(\theta) \quad (16)$$

Now if we choose  $\phi$  to be on the top :

$$\Gamma_{\nu\lambda}^\phi = \frac{1}{2} g^{\phi\phi} (\partial_\lambda g_{\phi\nu} + \partial_\nu g_{\phi\lambda} - \partial_\phi g_{\nu\lambda}) = \frac{1}{2} g^{\phi\phi} (\partial_\lambda g_{\phi\nu} + \partial_\nu g_{\phi\lambda}) \quad (17)$$

The only non-vanishing terms with  $\phi$  on the top are  $\Gamma_{\phi\theta}^\phi = \Gamma_{\theta\phi}^\phi$  :

$$\Gamma_{\phi\theta}^\phi = \frac{1}{2} g^{\phi\phi} \partial_\theta g_{\phi\phi} = \frac{\cos(\theta)}{\sin(\theta)} \quad (18)$$

We use the computed Christoffel's to write down the geodesic equation  $\ddot{x}^\mu + \Gamma_{\nu\rho}^\mu \dot{x}^\nu \dot{x}^\rho$  in the  $(\theta, \phi)$  coordinate. We find :

$$\begin{cases} \ddot{\theta} + \Gamma_{\phi\phi}^\theta \dot{\phi} \dot{\phi} = \ddot{\theta} - \sin(\theta) \cos(\theta) \dot{\phi} \dot{\phi} = 0 & \mu = \theta \\ \ddot{\phi} + 2\Gamma_{\theta\phi}^\phi \dot{\theta} \dot{\phi} = \ddot{\phi} + 2 \frac{\cos(\theta)}{\sin(\theta)} \dot{\theta} \dot{\phi} = 0 & \mu = \phi \end{cases} \quad (19)$$

Using the Euler-Lagrange equations with  $\mathcal{L} = \frac{1}{2}(\dot{\theta}^2 + \sin(\theta)^2 \dot{\phi}^2)$ , we get :

$$\begin{cases} \frac{d}{d\tau} \frac{\partial \mathcal{L}}{\partial \dot{\theta}} - \frac{\partial \mathcal{L}}{\partial \theta} = \frac{1}{2} \left( \frac{d}{d\tau} 2\dot{\theta} - 2 \sin(\theta) \cos(\theta) \dot{\phi}^2 \right) = 0 \\ \frac{d}{d\tau} \frac{\partial \mathcal{L}}{\partial \dot{\phi}} - \frac{\partial \mathcal{L}}{\partial \phi} = \frac{1}{2} \frac{d}{d\tau} \left( 2 \sin(\theta)^2 \dot{\phi} \right) = \sin(\theta)^2 \ddot{\phi} + 2 \cos(\theta) \sin(\theta) \dot{\theta} \dot{\phi} = 0 \end{cases} \quad (20)$$

which are the same equations as in (19).

We can easily see that the great circles  $(\theta(\tau), \phi(\tau)) = (\tau, \phi_0)$  on  $S^2$  are solutions to the equations just found. It is indeed the case because for that

particular solution  $\phi$  is constant along a great circle, witch implies  $\ddot{\phi} = \dot{\phi} = 0$  and simultaneously  $\theta(\tau) = \tau$  so that  $\ddot{\theta}$  vanishes. By looking at equation (19) or (20) we can see that every curb with  $\ddot{\theta} = \dot{\phi} = \phi = 0$  trivially satisfy both equations and therefore curbs like that are geodesics.

## 2. TENSOR ANALYSIS I: TENSOR ALGEBRA

- (a) Under a coordinate transformation  $x^\mu \rightarrow y^{\mu'}$  a function transforms such that his value at a fixed point remains the same :  $f(x^\mu) \rightarrow f'(y^{\mu'}) = f(x^\mu)$ . For the partial derivative of a function we have

$$\frac{\partial}{\partial x^\mu} f(x^\mu) \rightarrow \frac{\partial}{\partial y^{\mu'}} f'(y^{\mu'}) = \frac{\partial x^\mu}{\partial y^{\mu'}} \frac{\partial}{\partial x^\mu} f(x^\mu) = J_{\mu'}^\mu \frac{\partial}{\partial x^\mu} f(x^\mu) \quad (21)$$

which shows that  $\partial_\mu f$  is a covector. To simplify notation we define

$$J_{\mu'}^\mu = \frac{\partial x^\mu}{\partial y^{\mu'}} \quad \text{and} \quad J_\mu^{\mu'} = \frac{\partial y^{\mu'}}{\partial x^\mu} \quad (22)$$

which are the component of the Jacobian of the coordinate transformation and it's inverse.

- (b) By definition ( $A_{\mu\nu}$  and  $B^\mu$  being tensors) we have :

$$A_{\mu\nu} B^\nu \rightarrow A_{\mu'\nu'} B^{\nu'} = \left( J_{\mu'}^\mu J_{\nu'}^\nu A_{\mu\nu} \right) \left( J_\rho^{\nu'} B^\rho \right) = J_{\mu'}^\mu \delta_\rho^{\nu'} A_{\mu\nu} B^\rho = J_{\mu'}^\mu (A_{\mu\nu} B^\nu) \quad (23)$$

so that  $A_{\mu\nu} B^\nu$  transforms like a co-vector. The same goes for  $A_{\mu\nu} B^\mu B^\nu$  :

$$A_{\mu\nu} B^\mu B^\nu \rightarrow \left( J_{\mu'}^\mu J_{\nu'}^\nu A_{\mu\nu} \right) \left( J_\rho^{\mu'} B^\rho \right) \left( J_\lambda^{\nu'} B^\lambda \right) = \delta_\rho^\mu \delta_\lambda^\nu A_{\mu\nu} B^\rho B^\lambda = A_{\mu\nu} B^\mu B^\nu \quad (24)$$

witch transforms like a scalar.

- (c) The invariance of  $V(x)$  under coordinate transformations follows from the fact that partial derivatives are covectors and that they are contracted with a vector to form the field  $V(x)$ . By the chain rule, we see (again) that :

$$\partial_\mu = \frac{\partial}{\partial x^\mu} \rightarrow \partial_{\mu'} = \frac{\partial}{\partial y^{\mu'}} = \frac{\partial x^\mu}{\partial y^{\mu'}} \frac{\partial}{\partial x^\mu} = J_{\mu'}^\mu \partial_\mu \quad (25)$$

and with this we have :

$$V(x) \rightarrow V'(x) = V^{\mu'}(x) \partial_{\mu'} = (J_\mu^{\mu'} V^\mu)(J_\mu^{\nu'} \partial_\nu) = \delta_\mu^{\nu'} V^\mu \partial_\nu = V(x) \quad (26)$$

To see that  $A(x)$  is invariant too, we have to show that  $dx^\mu$  is a vector :

$$dx^\mu \rightarrow dy^{\mu'} = \frac{\partial y^{\mu'}}{\partial x^\mu} dx^\mu \quad (27)$$

and thus :

$$A(x) = A_\mu(x) dx^\mu \rightarrow A_{\mu'} dy^{\mu'} = (J_{\mu'}^\nu A_\nu)(J_\mu^{\mu'} dx^\mu) = A(x) \quad (28)$$

is also invariant under coordinate transformations.